Evaluation and Application of the AVIRIS Data for the Study of Coral Reefs **Zhongping Lee, Jianwei Wei** 26 **UMASS** Of Massachusetts **BOSTON**

Acknowledgements:

NASA HyspIRI Coral Reef and Volcano Research Program

Objective:

evaluate the quality of the remote-sensing reflectance (R_{rs}) derived from the new AVIRIS

- Evaluate and refine remote sensing algorithms developed for the detection of live corals;
- Obtain live coral coverage of the overflight regions from both video sampling and in situ R_{rs} with the most robust algorithm;
- Map live coral coverage of areas covered by the AVIRIS flight line with the robust algorithm after gain confidence of the AVIRIS R_{rs} ;
- Assess the impact of 30-m footprint on the detection and mapping of shallow-water coral reefs;
- Evaluate the relationship between live coral coverage and light availability



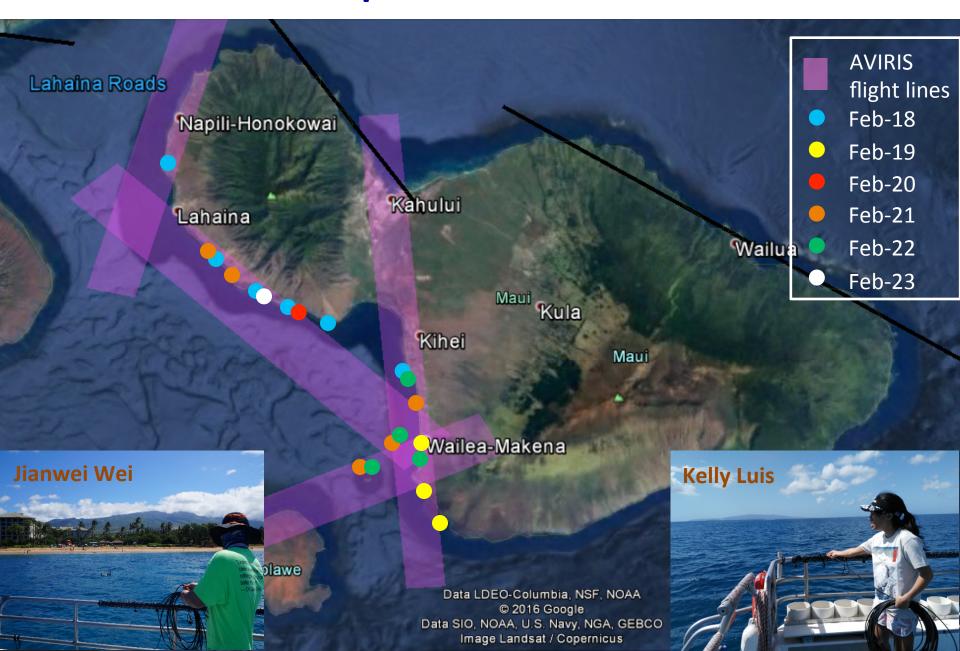




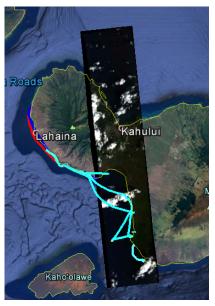
NASA HyspIRI Feb 2017 Hawaii Flights

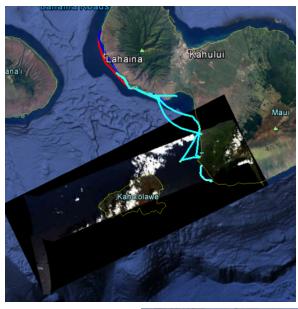


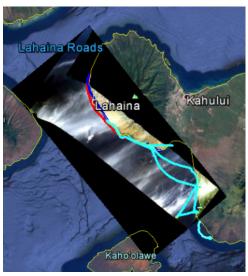
2017 In-situ Optical Observations in Maui



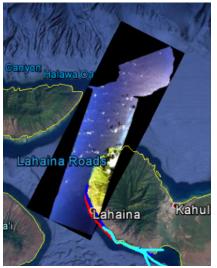
2017 In-situ Optical Observations in Maui

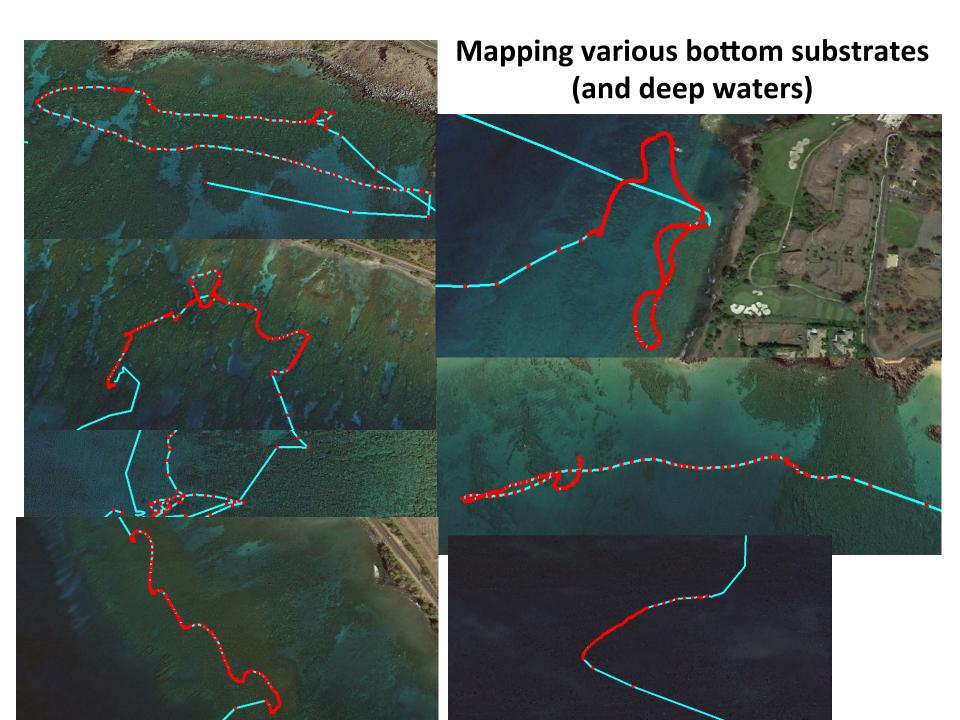




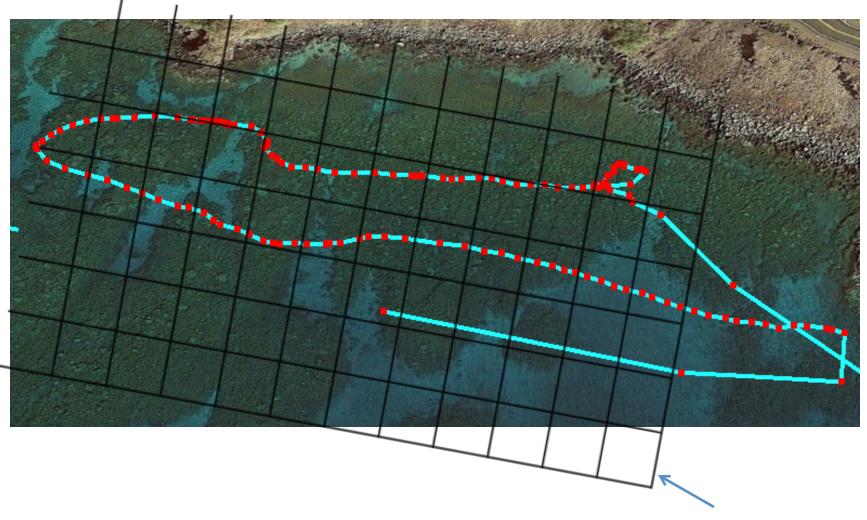




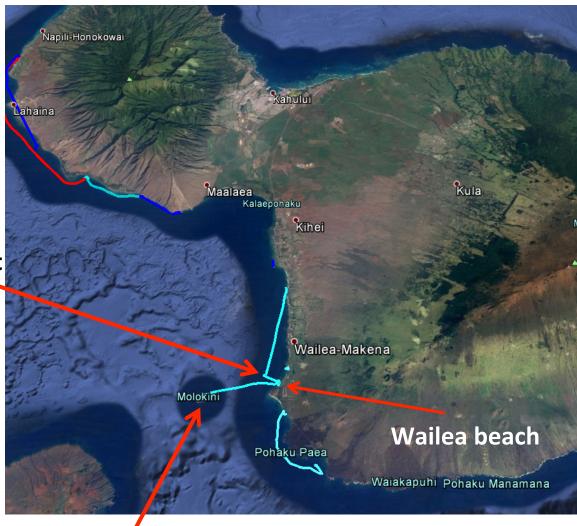




AVIRIS Remote Sensing Data Evaluation Scheme



AVIRIS image pixels (~15 m)

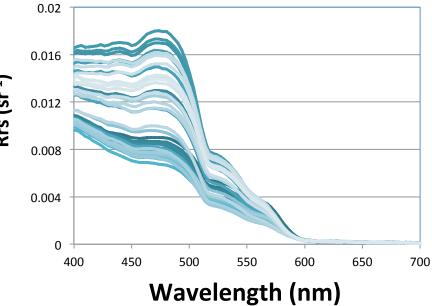


measurement

Deep water

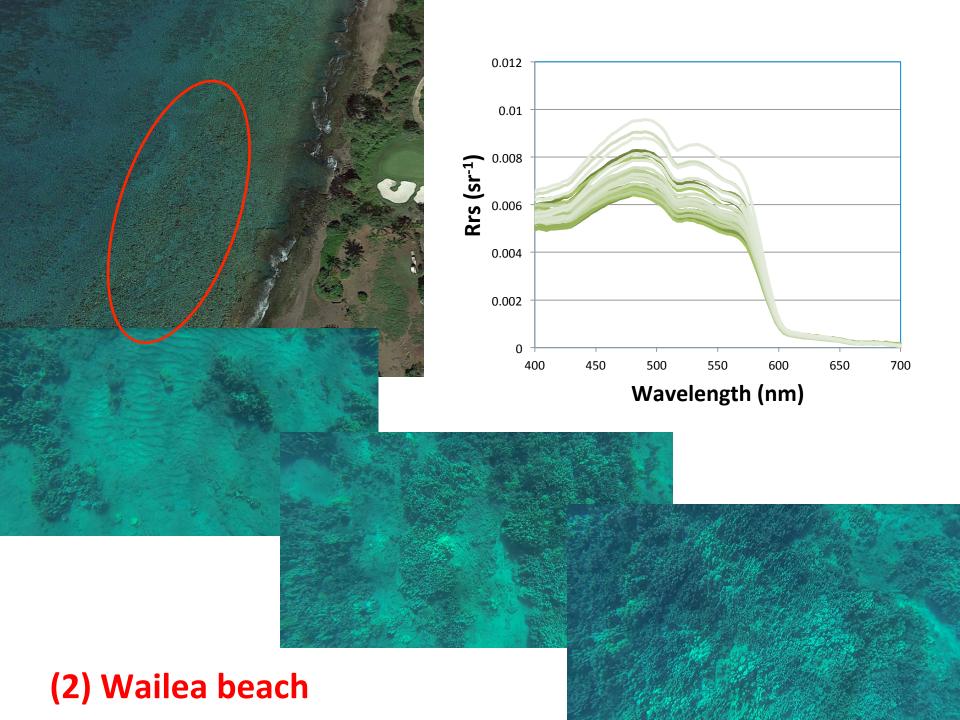
Molokini Atoll



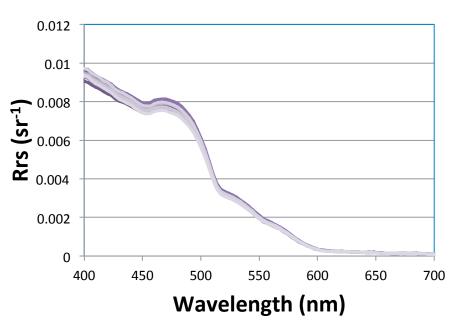




(1) Molokini Atoll







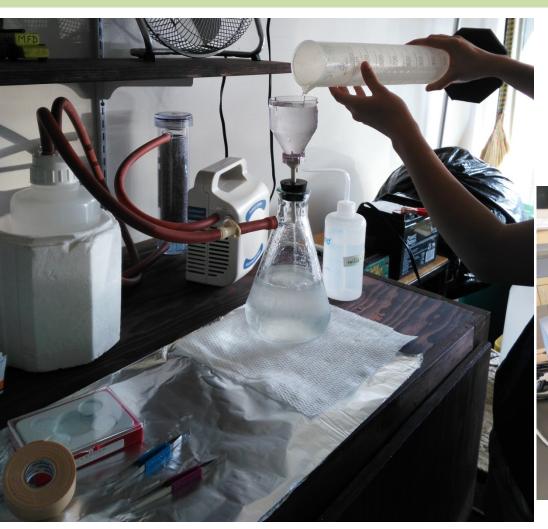


(3) Deep waters

At each transect (depths of 2-15 m), benthic videos (24 fps) were captured to facilitate further analysis.



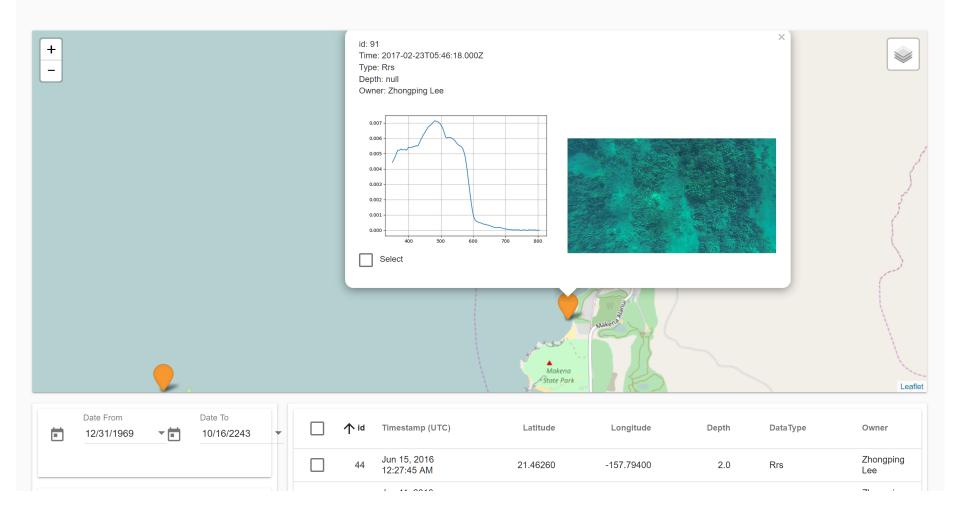
Water samples were also filtered to measure the light absorption properties of particles



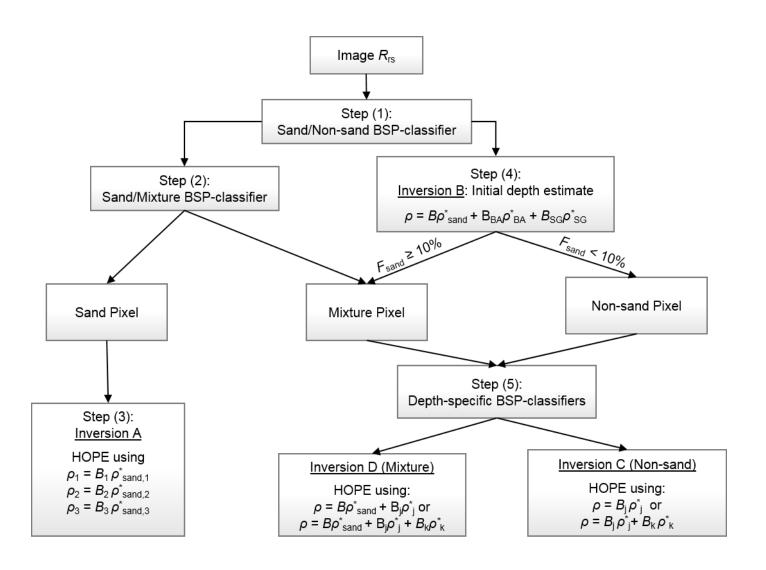
- 1) Phytoplankton absorption
- 2) Detritus absorption
- 3) Total particle absorption



VISA (Visualization of InSitu datA)



Algorithm to Remote Sense Bottom Substrates



Summary:

- 1. Successful field measurements to support AVIRIS overflight
- 2. Wide range of "end members" for the spectral reflectance of various bottom

 3. Data and a prototype algorithm has been developed for the remote sensing of bottom substrates.

Thank you!